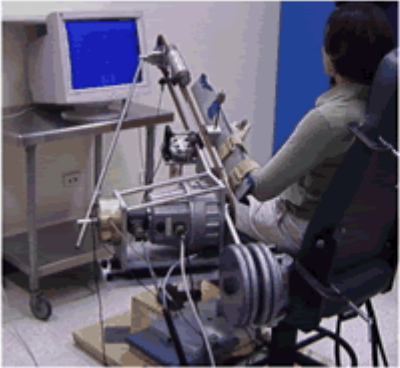
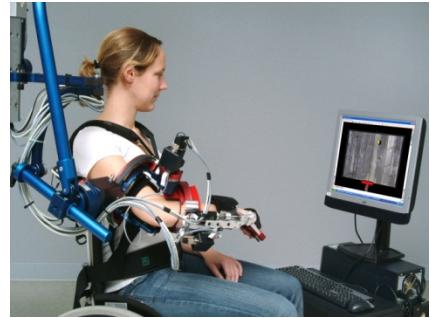





| Device                           | Target              | Motion Type        | Feedback  | Degree Of Freedom | Type Of Exercise   | Design   |
|----------------------------------|---------------------|--------------------|---|-------------------|--|--|
| Active Joint Brace for the Elbow | Proximal            | Active assistance  | Kinesthetic, proprioceptive, tactile and visual sensory.                                | N/A               | Elbow flexion and extension in a set of functionally oriented tasks tailored to each subject' motor abilities. | Mobile exoskeleton<br>EMG-controlled powered   |
| ARMGuide                         | Proximal            | Active-assisted    | Graphical feedback of the hand position and feedback on the amount of motor assistance. | 3                 | Reaching movements in different directions   | Singly-actuated<br><a href="http://www.rehab.research.va.gov/jour/00/37/6/reink376.htm">http://www.rehab.research.va.gov/jour/00/37/6/reink376.htm</a><br> |
| ARMin I and ARMin II             | Proximal and distal | Passive and active | Visual and auditory   | 6 independently   | Functional 3D workspace repetitive exercises   | Exoskeleton<br><a href="http://cabrr.cua.edu/devicegallery.cf">http://cabrr.cua.edu/devicegallery.cf</a>   |


Description of main devices  
**Robotics – upper extremity**

|        |          |   |          |   |  |  |
|--------|----------|---|----------|---|--|--|
|        |          |   |          | actuated<br>DOF and 1<br>coupled<br>DOF |  | <a href="#">m</a><br>   |
| BATRAC | Proximal | Passive                                   | Auditory | N/A                                     | Push and pull exercises in<br>bilateral mode | End-effector<br><br><a href="http://medicalxpress.com/news/2011-09-rewiring-brain-regain.html">http://medicalxpress.com/news/2011-09-rewiring-brain-regain.html</a><br> |
| BFIAMT | Proximal | Bilateral active<br>passive,<br>bilateral | Visual   | N/A                                     | Push and pull exercises.                     | End-effector   |

|                                     |        |   |        |   |   |   |
|-------------------------------------|--------|---|--------|---|---|---|
|                                     |        | reciprocal,<br>bilateral<br>passive,<br>bilateral<br>symmetric. |        |   |   |   |
| Bilateral Forearm and Wrist Trainer | Distal | Passive, active.  | N/A    | 1 | Supination movement of forearm and dorsiflexion/volarflexion of the wrist, bimanual, repetitive practice. | End-effector  |
| Bi-Manu-Track                       | Distal | Passive-passive,<br>passive-active,<br>active-active.           | Visual | 1 | Bilateral elbow pronation and supination, wrist flexion and extension in a mirror or parallel fashion.    | End-effector<br><br><a href="http://www.reha-stim.de/cms/index.php?id=60">http://www.reha-stim.de/cms/index.php?id=60</a><br><br> |

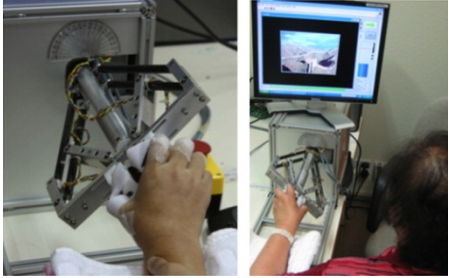
|                  |          |                                      |  |   |  |   |
|------------------|----------|--------------------------------------|--|---|--|---|
| Braccio di Ferro | Proximal | Adaptive control of robot assistance | Visual position of the hand and target, haptic feedback. | 2 | Shoulder and elbow movement in horizontal plane in a goal directed activity. | Actuated<br><a href="http://www.redorbit.com/news/technology/1836376/robot_teaches_stroke_survivors/">http://www.redorbit.com/news/technology/1836376/robot_teaches_stroke_survivors/</a><br><br><small>Vergaro et al., Journal of NeuroEngineering and Rehabilitation</small> |
|------------------|----------|--------------------------------------|--|---|--|---|

Description of main devices  
**Robotics – upper extremity**

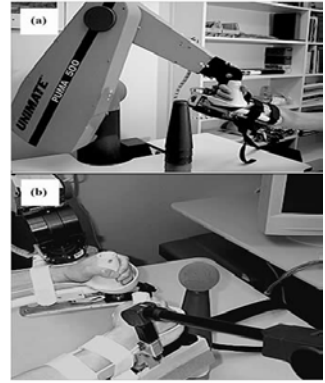
|            |          |                                     |  |   |  |   |
|------------|----------|-------------------------------------|--|---|--|---|
| GENTLE/S   | Proximal | Passive, active assisted or active. | Virtual reality haptic interface.          | 3 | Hand to mouth movements, reaching movements.                       | Exoskeleton<br><a href="http://www.mimics.ethz.ch/index.php?page_id=2">http://www.mimics.ethz.ch/index.php?page_id=2</a><br> |
| HandCare   | Distal   | Assisted                            | Visual                                     | 5 | Opening and closing movements in a goal directed exercises.        | End-effector  |
| HapticKnob | Distal   | Assisted, resistive                 | Interactive and intuitive visual feedback. | 2 | Grasping in coordination with pronation/supination of the forearm. | End-effector<br><a href="http://www.sciencedirect.com/science/article/pii/S0924424710000154">http://www.sciencedirect.com/science/article/pii/S0924424710000154</a>   |

Description of main devices

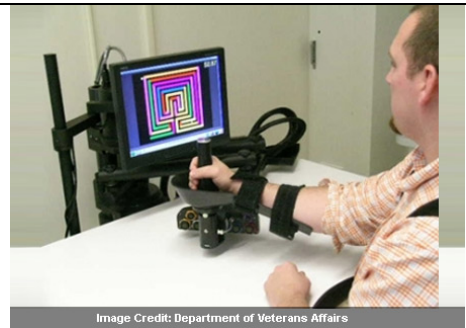
Robotics – upper extremity

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|--------|----------|--|--|-----|---|---|
|        |          |  |  |     |   |  |
| HWARD  | Distal   | Assisted, active assisted.                                     | Visual and auditory.   | 3   | Grasp and release movements in a virtual-environment (VR) setting.                                    | Pneumatically actuated  |
| L-EXOS | Proximal | Active assisted.   | Force feedback, visual feedback, auditory cueing during tasks.   | 5   | VR environment reaching, path following and free motion exercises.                                    | Exoskeleton   |
| MEMOS  | Proximal | Active, passive, active-assisted, resistive.                   | Visual feedback of the current position of the handle was provided.  | N/A | Elbow and shoulder exercises in a sequence point-to-point reaching movements in the horizontal plane. | Actuated, end-effector.   |
| MIME   | Proximal | Passive, active –assisted, active-constrained, bilateral modes | Feedback of the fraction of the movement completed or the time to complete was used to track and motivate performance. | 6   | Unilateral or bilateral shoulder and elbow movement in target reaching activities.                    | Exoskeleton   |

Description of main devices  
**Robotics – upper extremity**


|           |          |          |                               |   |   |  |
|-----------|----------|----------|-------------------------------|---|---|--|
|           |          |          |                               |   |   | <a href="http://www.rehab.research.va.gov/jour/06/43/5/lum.html">http://www.rehab.research.va.gov/jour/06/43/5/lum.html</a>  <p>Figure 1. Subjects performing (a) unilateral and (b) bilateral movements with Mirror Image Movement Enabler system.</p> |
| MIT-Manus | Proximal | Assisted | Visual, auditory, and tactile | 2 | Shoulder and elbow movement in horizontal plane, repetitive reaching exercises. | Exoskeleton<br><a href="http://www.techshout.com/science/2010/17/mit-manus-robot-assisted-therapy-may-help-stroke-patients-regain-function/">http://www.techshout.com/science/2010/17/mit-manus-robot-assisted-therapy-may-help-stroke-patients-regain-function/</a>   |

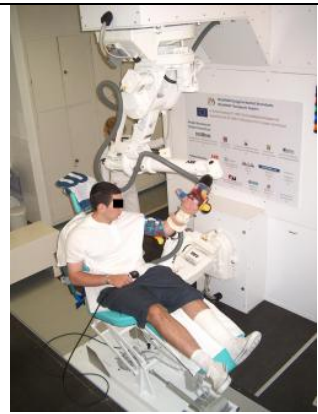
Description of main devices  
**Robotics – upper extremity**

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|---------|---------------------|-------------------------------|----------------------|---|---|---|
|         |                     |                               |                      |   |   |  <p>Image Credit: Department of Veterans Affairs</p>   |
|         | Proximal and distal | Assisted, resistive, passive. |                      | 3 | Abduction/adduction, flexion/extension, pronation/supination, vertical movements, grasping exercises.               | Exoskeleton   |
| NeReBot | Proximal            | Assisted.                     | Visual and auditory. | 3 | Flexion and extension, pronation and supination, adduction and abduction, circular movements of shoulder and elbow. | <p>Direct drive wire actuation, can be used in sitting or lying positions.</p> <p><a href="http://www.mechatronics.it/index.php?lingua=ENG&amp;pag=res&amp;sub=att&amp;id=16">http://www.mechatronics.it/index.php?lingua=ENG&amp;pag=res&amp;sub=att&amp;id=16</a></p> |





Description of main devices  
**Robotics – upper extremity**

|                            |          |                                   |                      |     |  |  |
|----------------------------|----------|-----------------------------------|----------------------|-----|--|--|
|                            |          |                                   |                      |     |  |                   |
| Pneumatic Glove            | Distal   | Assisted, assist as needed.       | Haptic, visual .     | 5   | Grasp release tasks, digit extension with VR environment and real objects  | Exoskeleton  |
| RegoGo                     | Proximal | Passive, active, active assisted. | Visual and auditory. | N/A | Reaching objectives on the computer screen using elbow and shoulder joints, in 3 dimensions and on all spatial planes. | End-effector   |
| REHAROB Therapeutic System | Proximal | Passive assistance                | N/A                  | N/A | Shoulder and elbow physiotherapy, executing exercises slowly and with constant velocity in a high repetition number.   | Exoskeleton<br><a href="http://www.a1tech.hu/reharob_en.htm">http://www.a1tech.hu/reharob_en.htm</a> |

|   |                     |  |   |     |  |  |
|---|---------------------|--|---|-----|--|--|
|   |                     |  |   |     |  |   |
| Robot-Assisted Individualized Finger Rehabilitation | Distal              | Full passive, assisted.  | N/A   | N/A | Simulated grasping and releasing training, VR based recreational activity. | End -effector  |
| T-WREX and Pneu-WREX                                | Proximal and distal | Passive (non-robotic) arm orthosis that provides support for the arm against gravity | Auditory and visual feedback, objective feedback of task performance at end of each game. | 5   | Functional exercises in 3D/Virtual environment tasks, repetitive.          | Exoskeleton<br><a href="http://www.ric.org/research/centers/mars3/archives/mars-rerc/twrexdesc/">http://www.ric.org/research/centers/mars3/archives/mars-rerc/twrexdesc/</a> |

Description of main devices  
**Robotics – upper extremity**

|  |          |                  |                     |   |  |   |
|--|----------|------------------|---------------------|---|--|---|
|  |          |                  |                     |   |  |    |
|  | Proximal | Assist as needed | Auditory and visual | 4 | Elbow flexion/extension, shoulder horizontal abduction/adduction, shoulder flexion/extension, and forward/backward translation , functional 3D tasks | <p>Exoskeleton</p> <p><a href="http://www.readcube.com/articles/10.1186/1743-0003-6-20">http://www.readcube.com/articles/10.1186/1743-0003-6-20</a></p>  |